

# Spring 2008 Lecture 9

## SLAB ANALYSIS FOR FLAT

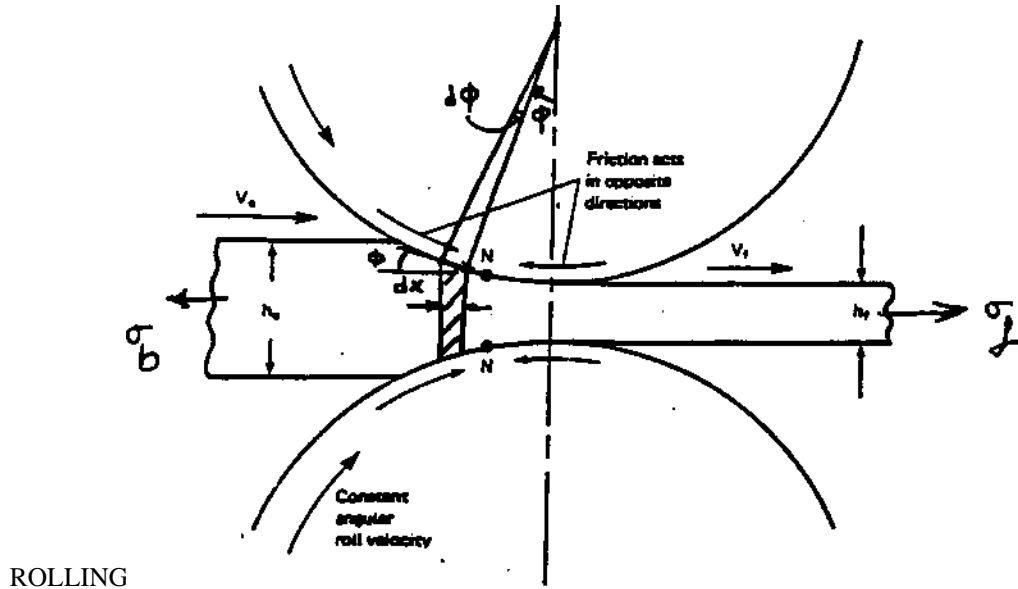


Figure 1: Schematic of flat rolling showing the neutral point

$$\begin{aligned} \sum F_x = 0 \Rightarrow & (\sigma_x + d\sigma_x)(h + dh) - \sigma_x h \\ & \mp (2\mu p R d\phi) \cos\phi \\ & + 2p R d\phi \sin\phi \end{aligned} \quad (1)$$

$- = \text{entry}$   
 $+ = \text{exit}$

$$\sigma_x h + \sigma_x dh + h d\sigma_x + \underbrace{dh d\sigma_x}_{\text{zero}} - \sigma_x h \mp 2\mu p R d\phi \cos\phi + 2p R d\phi \sin\phi = 0 \Rightarrow$$

$$\begin{aligned} \left. \begin{aligned} \frac{d(\sigma_x h)}{d\phi} &= 2pR(-\sin\phi \pm \mu \cos\phi) \\ \text{Small angles: } \sin\phi &\approx \phi \\ \cos\phi &\approx 1 \end{aligned} \right] \Rightarrow \\ \frac{d(\sigma_x h)}{d\phi} &= 2pR(-\phi \pm \mu) \end{aligned} \quad (2)$$

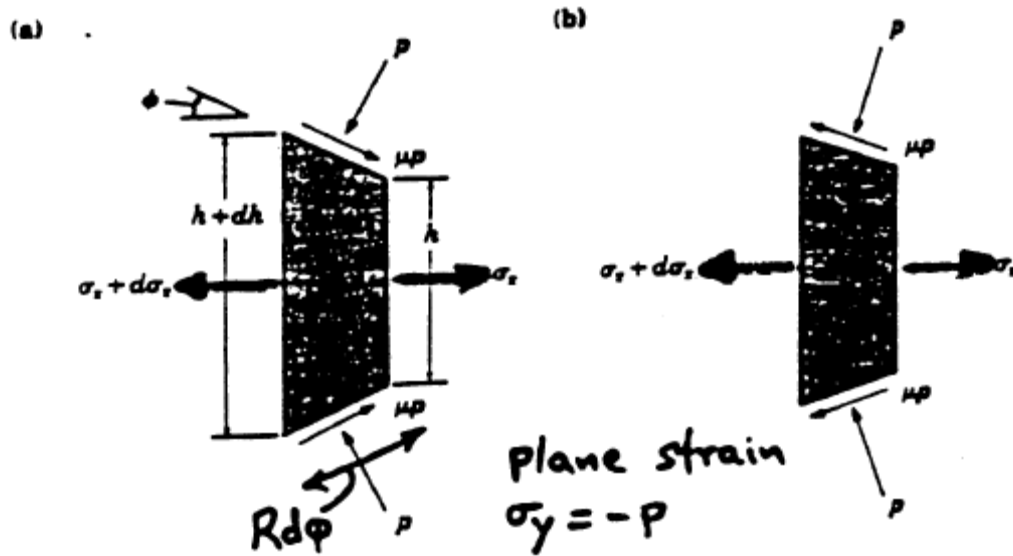


Figure 2: Stresses on an element in rolling: (a) entry zone and (b) exit zone

For small angles take  $\sigma_z \simeq -p$  and for plane strain ( $\epsilon_y = 0$ )  $\Rightarrow$

$$\underbrace{\sigma_x + p = \frac{2}{\sqrt{3}}Y}_{\text{true anywhere inside the deformation zone}} \quad (Y = \text{Yield Stress}) \quad (3)$$

true anywhere inside the deformation zone

$h$  changes with  $\phi$  as follows:

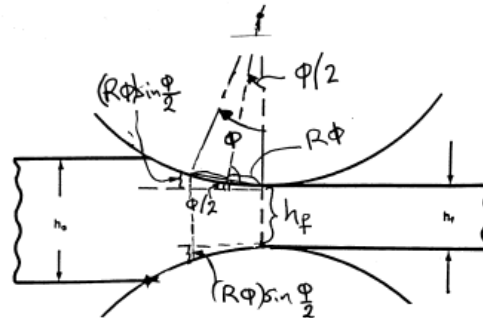


Figure 3: Approximation of  $h$  in terms of  $\phi$ .

$$\begin{aligned} h &= h_f + 2(R\phi) \sin \frac{\phi}{2} \\ &= h_f + 2(R\phi) \frac{\phi}{2} \\ &= h_f + R\phi^2 \end{aligned} \quad (4)$$

We assume that as the material advances inside the deformation zone, its hardening behavior is such that:  $Yh = \text{constant}$  (so as  $h$  decreases,  $Y$  increases such that the product  $Yh$  remains constant!!! A ridiculous assumption that however is better than assuming that  $Y$  is constant inside the deformation zone!).

Returning to the equilibrium equation with the above assumption, we can write:

$$\begin{aligned} \frac{d(\sigma_x h)}{d\phi} &= \frac{d\left(\frac{2}{\sqrt{3}}Y - p\right)h}{d\phi} = \underbrace{\frac{2}{\sqrt{3}} \frac{d(Yh)}{d\phi}}_{\text{zero}} - \frac{d(ph)}{d\phi} \\ &= -\frac{d(ph)}{d\phi} = -\frac{d\left(p\frac{1}{Y}Yh\right)}{d\phi} = -\frac{d(p/Y)}{d\phi} \underbrace{Yh}_{\text{const}} \end{aligned} \quad (5)$$

Finally

$$\begin{aligned} -\frac{d\left(\frac{p}{Y}\right)}{d\phi} Yh &= 2pR(-\phi \pm \mu) \Rightarrow \\ -\frac{d\left(\frac{p}{Y}\right)}{\frac{p}{Y}} &= 2R \frac{-\phi \pm \mu}{h} d\phi \Rightarrow \\ \boxed{-\frac{d\left(\frac{p}{Y}\right)}{\frac{p}{Y}} &= 2R \frac{-\phi \pm \mu}{h_f + R\phi^2} d\phi} \end{aligned} \quad (6)$$

Let us integrate the above equation in the entry region from  $j = a$  to a general angle  $j$ . Similar calculation can be applied to the exit region

$$-\int_{\text{entry}}^{\phi} \frac{d\left(\frac{p}{Y}\right)}{\frac{p}{Y}} = 2R \int_{\text{entry}}^{\phi} \frac{-\phi + \mu}{h_f + R\phi^2} d\phi \Rightarrow \quad (7)$$

$$\begin{aligned} -\left(\ln \frac{p}{Y} - \ln \frac{p}{Y} \Big|_{\text{entry}}\right) &= -\ln(h_f + R\phi^2) + \ln(h_f + R\alpha^2) \\ + 2R\mu \frac{1}{\sqrt{h_f R}} &\left(\tan^{-1} \sqrt{\frac{R}{h}} \phi - \tan^{-1} \sqrt{\frac{R}{h}} \alpha\right) \end{aligned} \quad (8)$$

Note that in the last calculation we used the following integral formula:

$$\int \frac{dx}{a^2 + b^2 x^2} = \frac{1}{ab} \arctan \frac{bx}{a}, \quad (\arctan \equiv \tan^{-1}) \quad (9)$$

At the entry region using the yield condition, one can write the following:

$$\frac{p}{Y} \Big|_{\text{entry}} = \frac{\frac{2Y}{\sqrt{3}} - \sigma_x}{Y} \Big|_{\text{entry}} = \left(\frac{2}{\sqrt{3}} - \frac{\sigma_b}{Y_{\text{entry}}}\right) = \frac{2}{\sqrt{3}} \left(1 - \frac{\sigma_b}{Y'_{\text{entry}}}\right) \quad (10)$$

where  $Y'_{\text{entry}} = \frac{2}{\sqrt{3}} Y_{\text{entry}}$ .

So returning to equation (8), we can write:

$$\begin{aligned}
& -\ln \frac{p}{Y} + \ln \frac{2}{\sqrt{3}} \left( 1 - \frac{\sigma_b}{Y'_{\text{entry}}} \right) \\
= & -\ln \left( \overbrace{h_f + R\phi^2}^h \right) + \ln \left( \overbrace{h_f + R\alpha^2}^{h_o} \right) \\
+ & 2R\mu \frac{1}{\sqrt{h_f R}} \left( \tan^{-1} \sqrt{\frac{R}{h}} \phi - \tan^{-1} \sqrt{\frac{R}{h}} \alpha \right)
\end{aligned} \tag{11}$$

Where

$$\begin{aligned}
H &= 2\sqrt{\frac{R}{h_f}} \tan^{-1} \left( \sqrt{\frac{R}{h_f}} \phi \right) \\
H_o &= 2\sqrt{\frac{R}{h_f}} \tan^{-1} \left( \sqrt{\frac{R}{h_f}} \overbrace{\alpha}^{\text{entry}} \right)
\end{aligned} \tag{12}$$

Where Equation (11) is now simplified as:

$$\begin{aligned}
& -\ln \frac{\frac{p}{Y} h_o}{\frac{2}{\sqrt{3}} \left( 1 - \frac{\sigma_b}{Y'_{\text{entry}}} \right) h} = \mu (H - H_o) \Rightarrow \\
& -\ln \frac{\frac{p}{Y'} h_o}{h \left( 1 - \frac{\sigma_b}{Y'_{\text{entry}}} \right)} = \mu (H - H_o) \\
& \ln \frac{\frac{p}{Y'} h_o}{h \left( 1 - \frac{\sigma_b}{Y'_{\text{entry}}} \right)} = \mu (H_o - H)
\end{aligned} \tag{13}$$

Finally, the following pressure distribution is derived in the entry region:

$$\frac{p}{Y'} = \left( 1 - \frac{\sigma_b}{Y'_{\text{entry}}} \right) \frac{h}{h_o} e^{\mu(H_o - H)} \tag{14}$$

where  $H$  and  $H_o$  are given by equation (12).

To derive the corresponding equation in the exit region, you can repeat the above calculations by integrating equation (6) (with the bottom sign in  $\pm$ ) from angle  $f$  to angle 0 (exit). It is also possible to derive the distribution of  $p$  at the exit using equation (14) with some changes!

$$\left( \begin{array}{l} \text{here } h_o \rightarrow h_f, \quad Y'_{\text{entry}} \rightarrow Y'_{\text{exit}} \\ H_o \rightarrow 0 \text{ (because } \alpha = \phi_{\text{at the exit}} = 0) \end{array} \right) \quad (15)$$

$$\frac{p}{Y'} = \left( 1 - \frac{\sigma_f}{Y'_{\text{exit}}} \right) \frac{h}{h_f} e^{\mu H} \quad (16)$$

Equations (14) and (16) define the complete pressure distribution in the deformation zone.

### Calculation of the Neutral Point

Equate the two pressure expressions from equations (14) and (16):

$$\left( 1 - \frac{\sigma_b}{Y'_{\text{entry}}} \right) \frac{h}{h_o} e^{\mu(H_o-H)} = \left( 1 - \frac{\sigma_f}{Y'_{\text{exit}}} \right) \frac{h}{h_f} e^{\mu H} \quad (17)$$

$$\Rightarrow e^{\mu(2H-H_o)} = \frac{1 - \frac{\sigma_b}{Y'_{\text{entry}}} \frac{h_f}{h_o}}{1 - \frac{\sigma_f}{Y'_{\text{exit}}} \frac{h_f}{h_o}} \quad (18)$$

Simplifying for the case  $\sigma_b = \sigma_f = 0$  leads to:

$$H_n = \frac{1}{2} \left( H_o - \frac{1}{\mu} \ln \frac{h_o}{h_f} \right) \quad (19)$$

$$2\sqrt{\frac{R}{h_f}} \tan^{-1} \left( \sqrt{\frac{R}{h_f}} \phi_n \right) = H_n \Rightarrow \quad (20)$$

$$\boxed{\phi_n = \sqrt{\frac{h_f}{R}} \tan \left( \sqrt{\frac{h_f}{R}} \frac{H_n}{2} \right)} \quad (21)$$